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# Probabilistic Flood Forecasting

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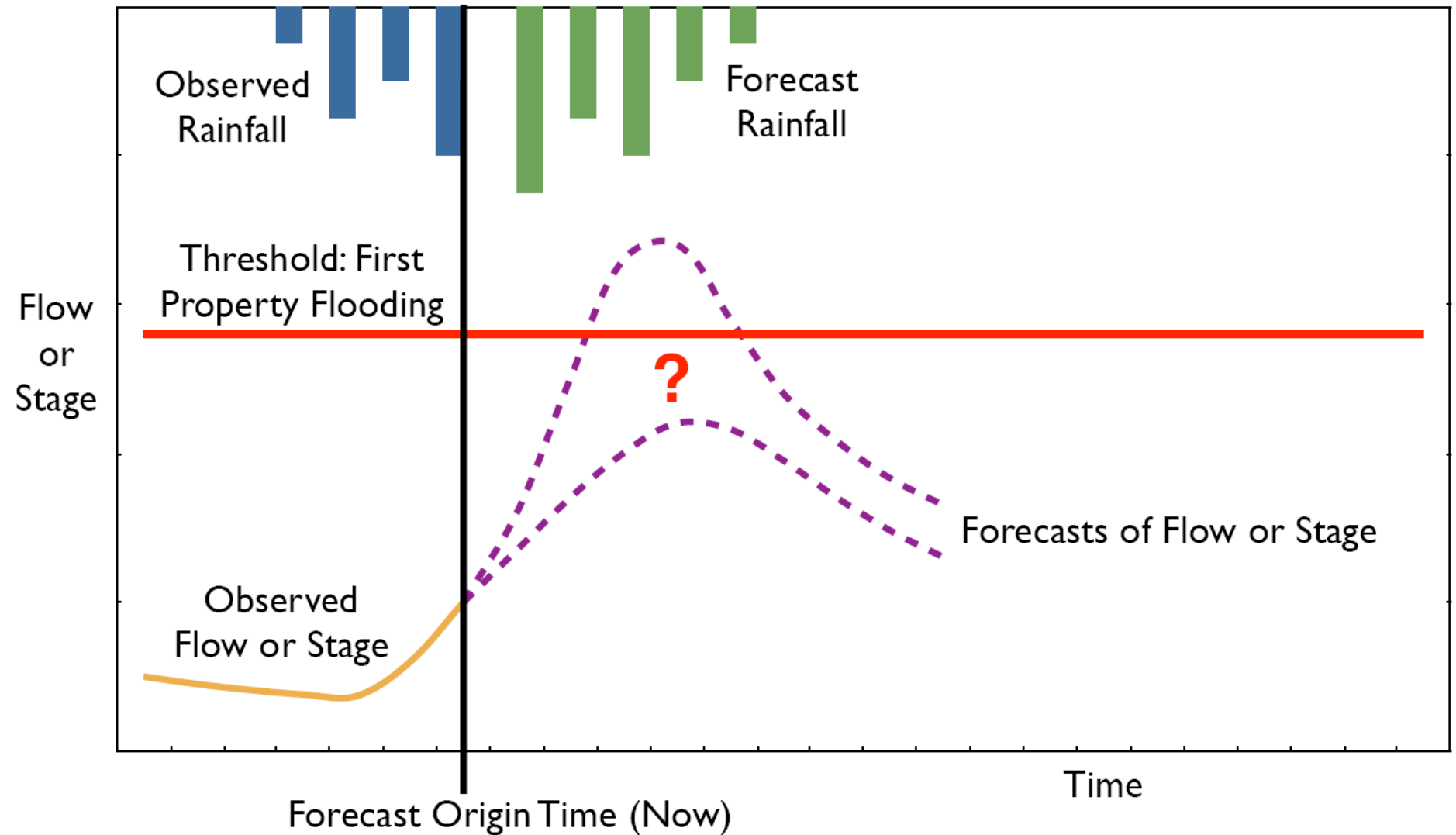
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# Acknowledgements

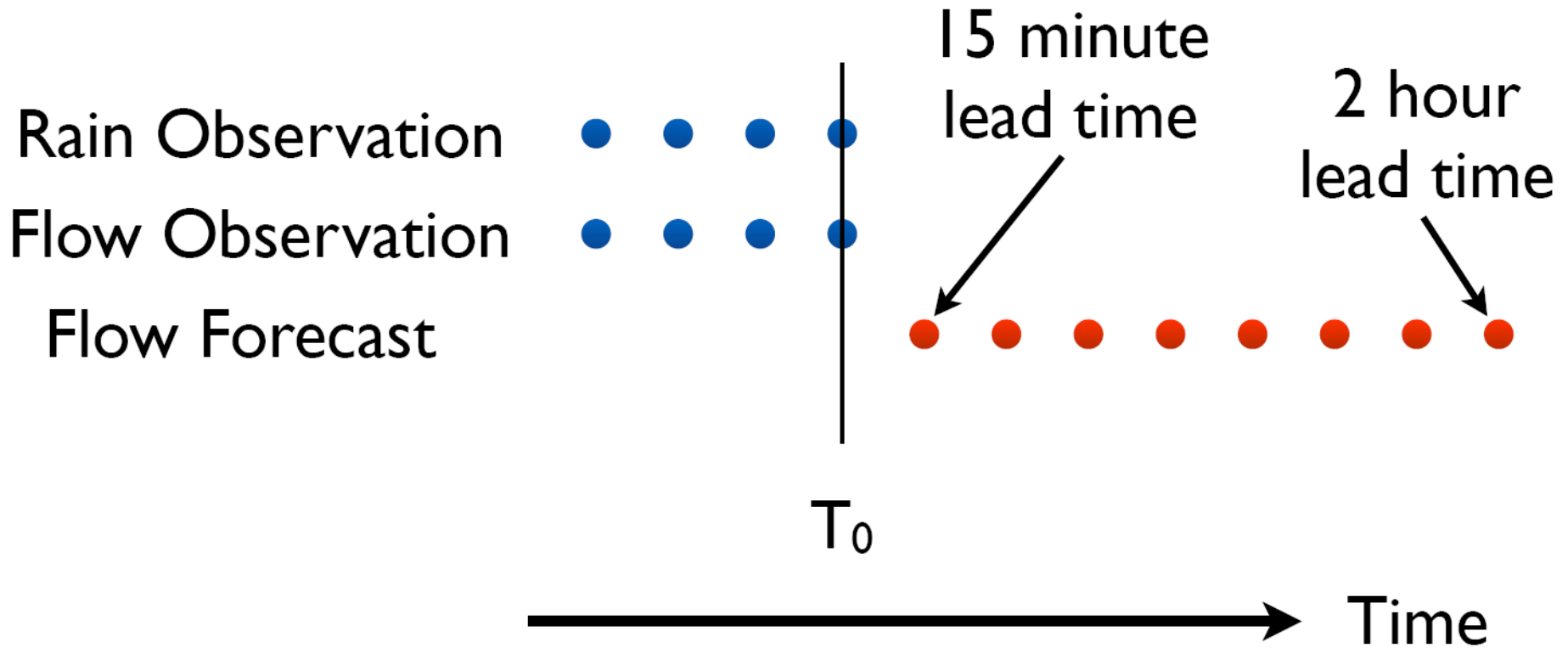
- ➔ Richard Cross
- ➔ Tim Harrison
- ➔ Stefan Laeger
- ➔ Paul Wass (JBA Consulting)
- ➔ Rob Lamb (JBA Consulting)
- ➔ ... and others

# What is real-time flood forecasting?

# What do we forecast?



# Lead time



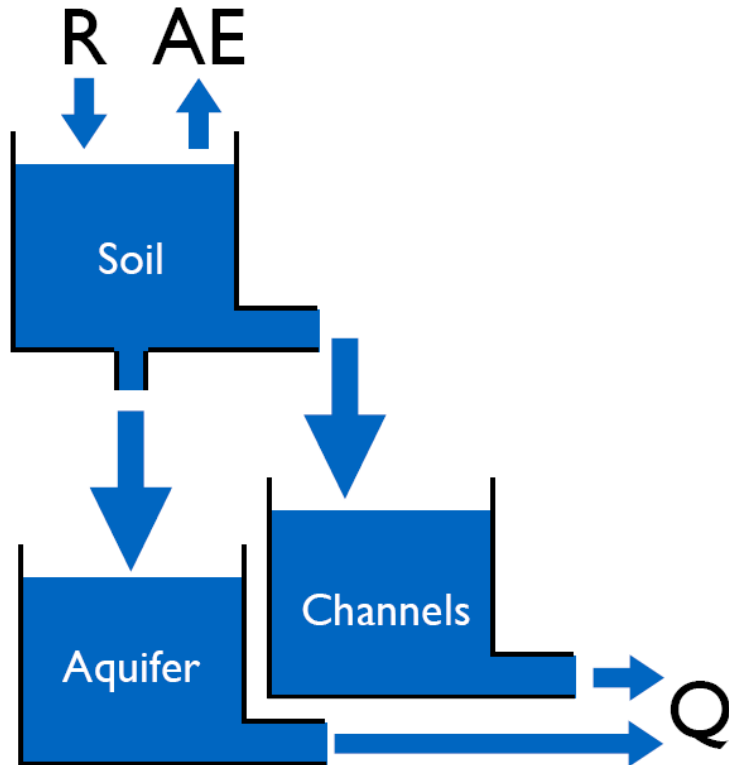
(Timestep = 15 minutes, for example)

# Forecasting models

- ➔ Rainfall-runoff
- ➔ River routing
- ➔ Real-time updating
  - ➔ Error prediction / correction
  - ➔ Data assimilation
- ➔ Cascades of rainfall-runoff and routing models

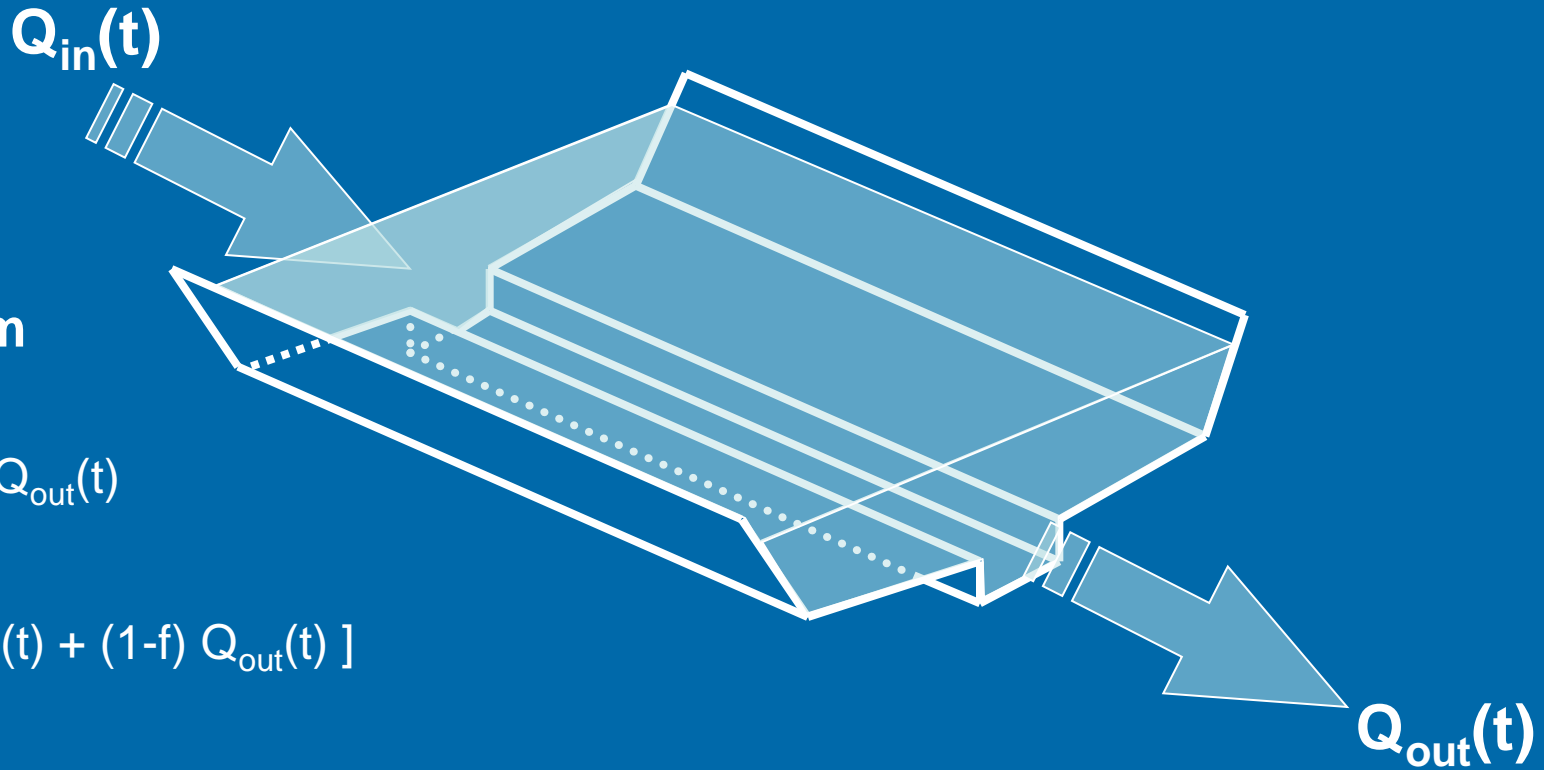


# Conceptual rainfall-runoff models



- Model structure
- Parameters
  - Rainfall
  - Potential evaporation
- Initial conditions
- Outputs
  - Discharge
  - Actual evaporation

# River routing models



Muskingham

$$\frac{dS}{dt} = Q_{in}(t) - Q_{out}(t)$$

$$S(t) = k [ f Q_{in}(t) + (1-f) Q_{out}(t) ]$$

$$Q_{out}(t+\Delta t) = c_1 Q_{in}(t+\Delta t) + c_2 Q_{in}(t) + c_3 Q_{out}(t)$$

# Real-time updating

- ➔ State updating
- ➔ Error prediction / correction
- ➔ Parameter updating

# Empirical State Updating

Prediction error

$$\epsilon_t = Q_t^{(sim)} - Q_t^{(obs)}$$

2 Parallel flow paths

$$Q_t^{(sim)} = q_{b,t} + q_{s,t}$$

Updated flows

$$q_{b,t}^* = q_{b,t} + \alpha g_b \epsilon_t$$
$$q_{s,t}^* = q_{s,t} + (1 - \alpha) g_s \epsilon_t$$
$$\alpha = \frac{q_b}{(q_s + q_b)}$$

Moore, 2007 (Hyd. Earth. Sys. Sci.)

# Error Prediction / Correction

$$\varepsilon_t = Q_t^{(sim)} - Q_t^{(obs)}$$

AR Model

$$\varepsilon_t = a_1\varepsilon_{t-1} + a_2\varepsilon_{t-2} + \cdots + a_n\varepsilon_{t-n} + \epsilon_t$$

Recursive Prediction

$$\hat{\varepsilon}_{t_0+k|t_0} = a_1\hat{\varepsilon}_{t_0+k-1|t_0} + a_2\hat{\varepsilon}_{t_0+k-2|t_0} + \cdots + a_n\hat{\varepsilon}_{t_0+k-n|t_0}$$

# Stage (water level) forecasts

**Rating curve** used to convert flow forecasts from rainfall-runoff or simple river routing models

$$Q = \begin{cases} C_1(H - a_1)^{b_1} & H_1 \leq H < H_2 \\ C_2(H - a_2)^{b_2} & H_2 \leq H < H_3 \\ C_3(H - a_3)^{b_3} & H_3 \leq H < H_4 \\ \vdots & \text{etc} \end{cases}$$

Hydrodynamic model

flow and stage are both model outputs

# What is probabilistic flood forecasting?

# Probabilistic forecasting

- ➔ Accept all forecasts are uncertain / in error
- ➔ Want objective way of indicating the uncertainty
- ➔ Particularly important for longer lead-times
  - ➔ But shorter lead-times too
- ➔ Forecasts of probability distributions
  - ➔ (or statistics thereof)
- ➔ Probabilistic not the only way
  - ➔ But may be useful for formal decision making

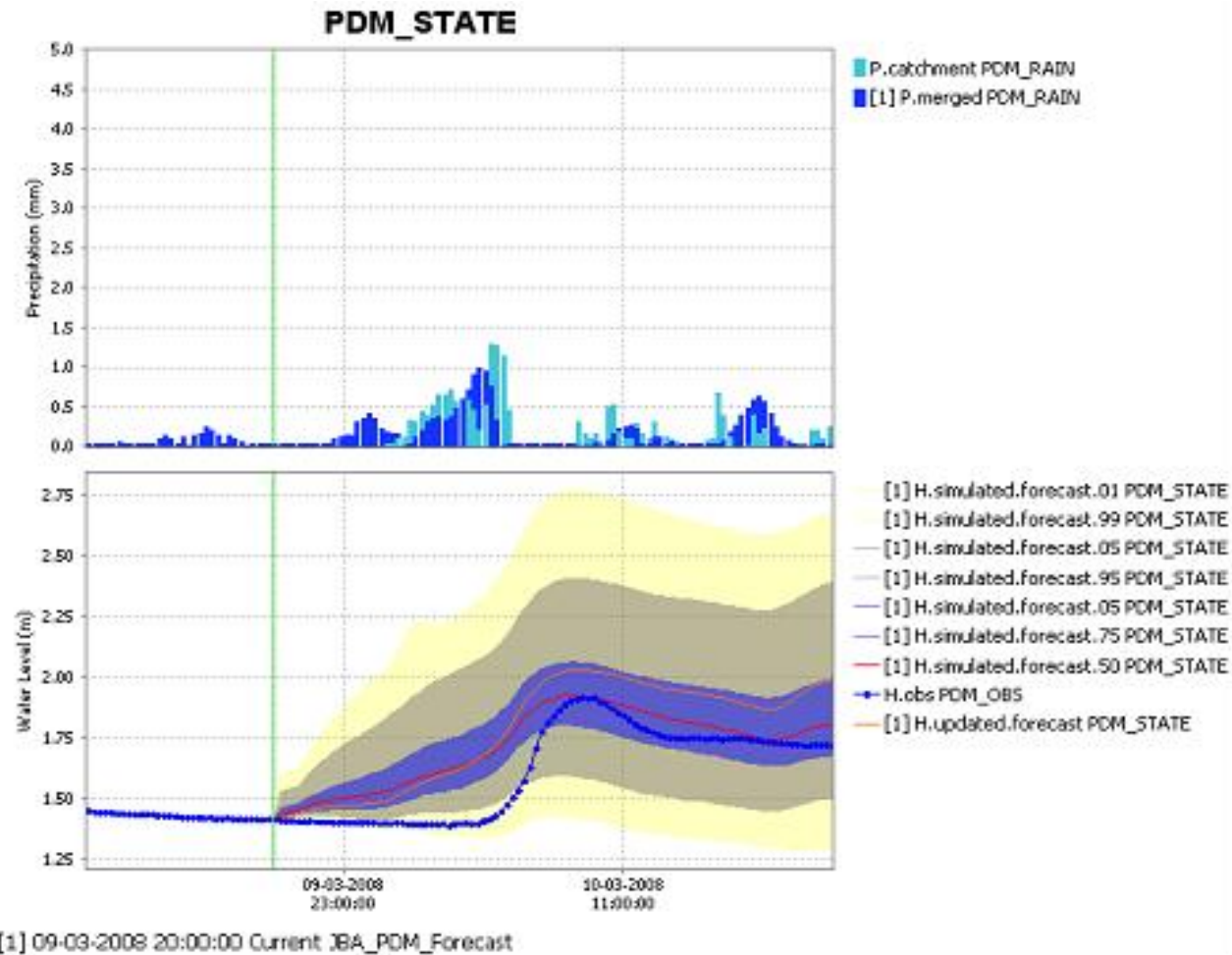


# Approaches to probabilistic flood forecasting

- ➔ Forecast conditioning
  - ➔ Historic Forecast Performance Tool / Quantile Regression (HFPT / QR)
- ➔ Updating using a stochastic scheme
- ➔ Stochastic models
- ➔ Forward uncertainty propagation
  - ➔ Rainfall ensembles

# Proposed method

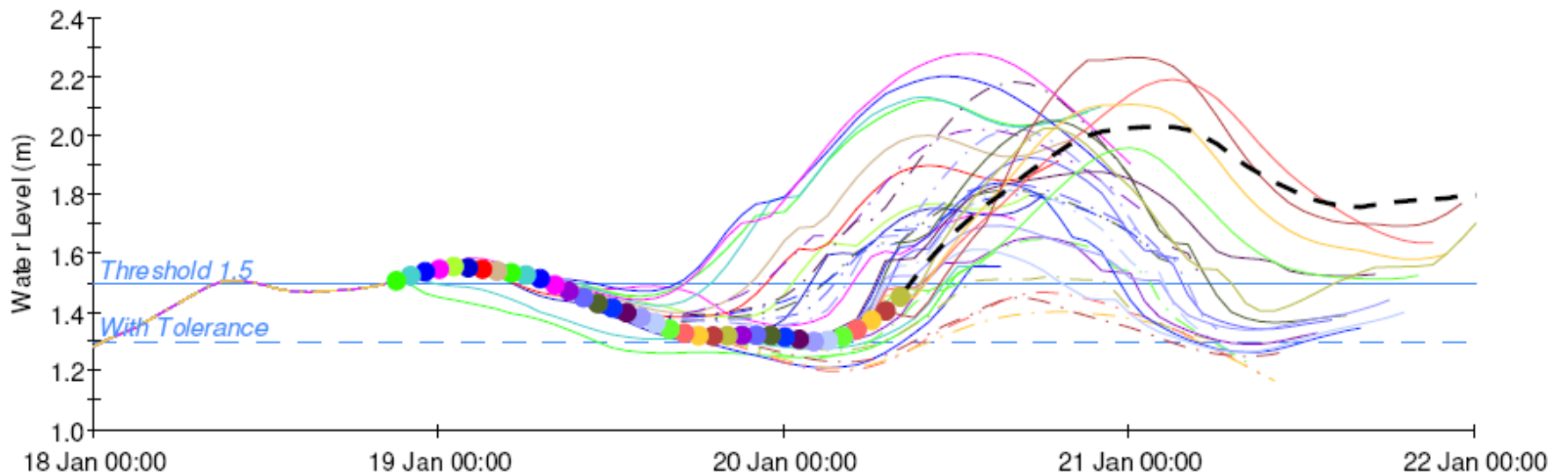
# Example of HFPT in NFFS



# How HFPT / QR works

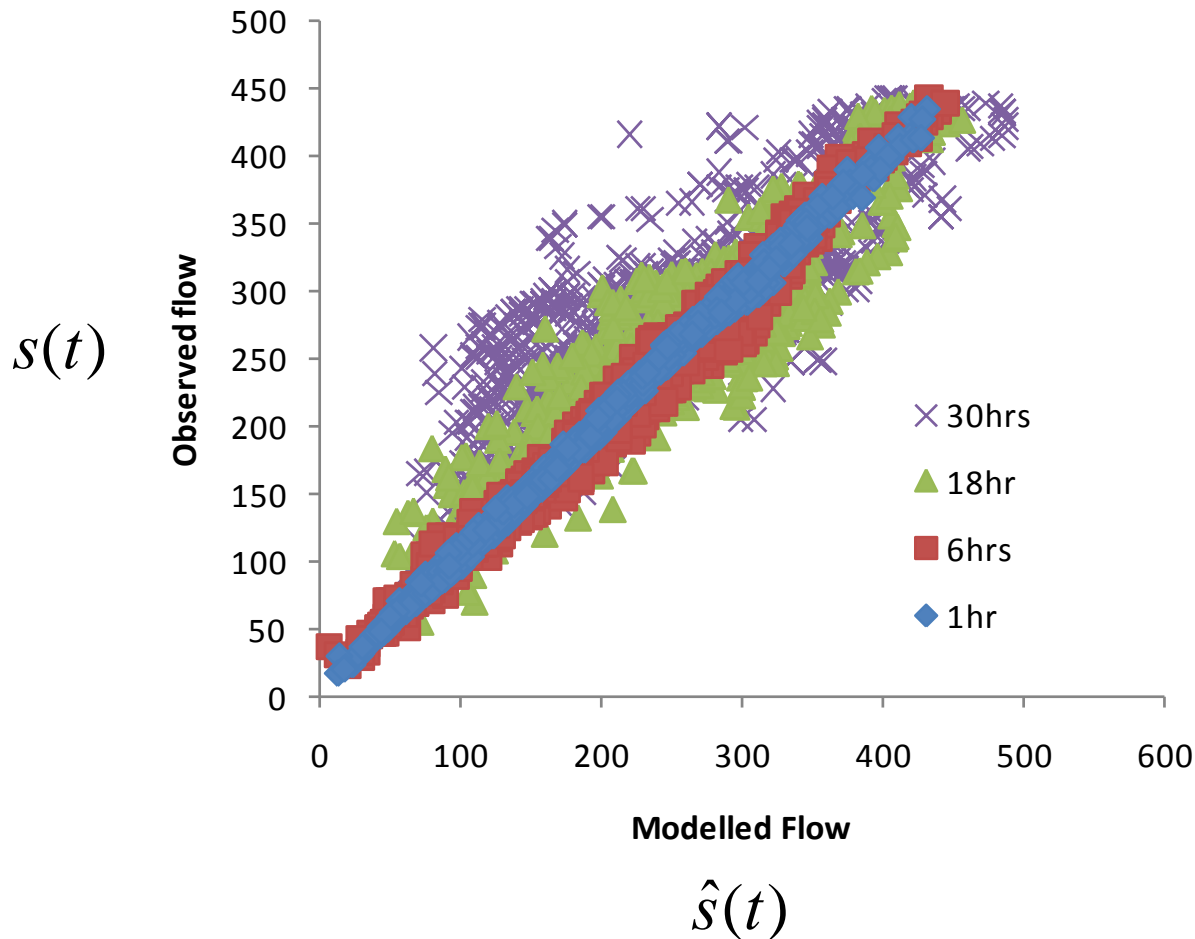
- ➔ Analysis of historic forecasts
- ➔ Additive error
- ➔ Use QR to fit linear relationships between error quantiles (at a given lead-time) and forecast magnitude
  - ➔ NQT to transform to Gaussian domain
- ➔ Adjustment to prevent quantiles crossing
- ➔ Look-up table of error quantile as a function of forecast magnitude (for given lead-time)
  - ➔ NQT inverted
  - ➔ Intermediate lead-times interpolated

# Example forecasts for a single event



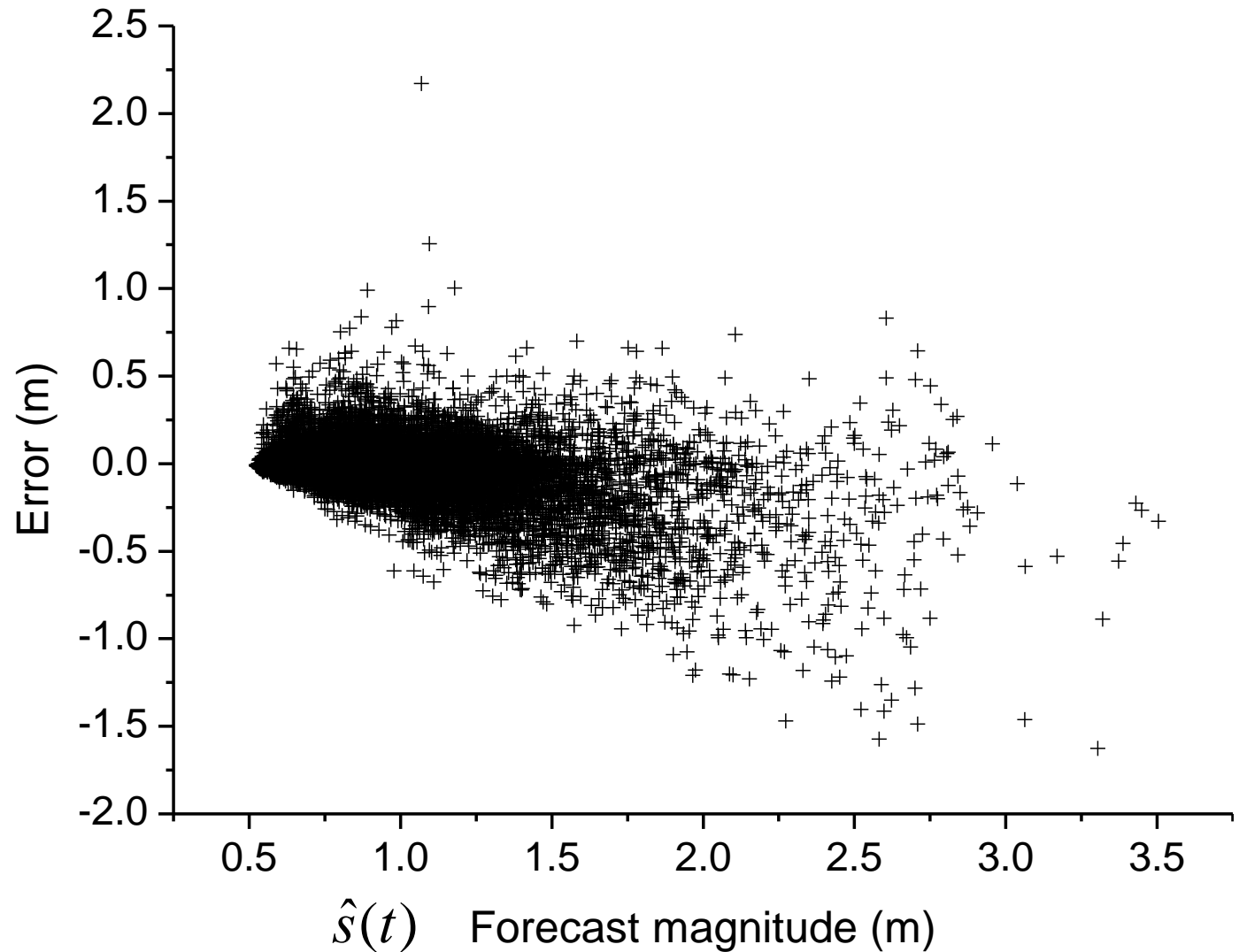
# Pairs of forecasts and observations at lead times

**Figure Error! No text of specified style in document.-1 : Pairs of observed and modelled values extracted from performance evaluation study at four lead times (River Ouse at Viking)**



# Forecast errors related to magnitude for a lead time

$$e(t) = s(t) - \hat{s}(t)$$



# Normal Quantile Transform (NQT)

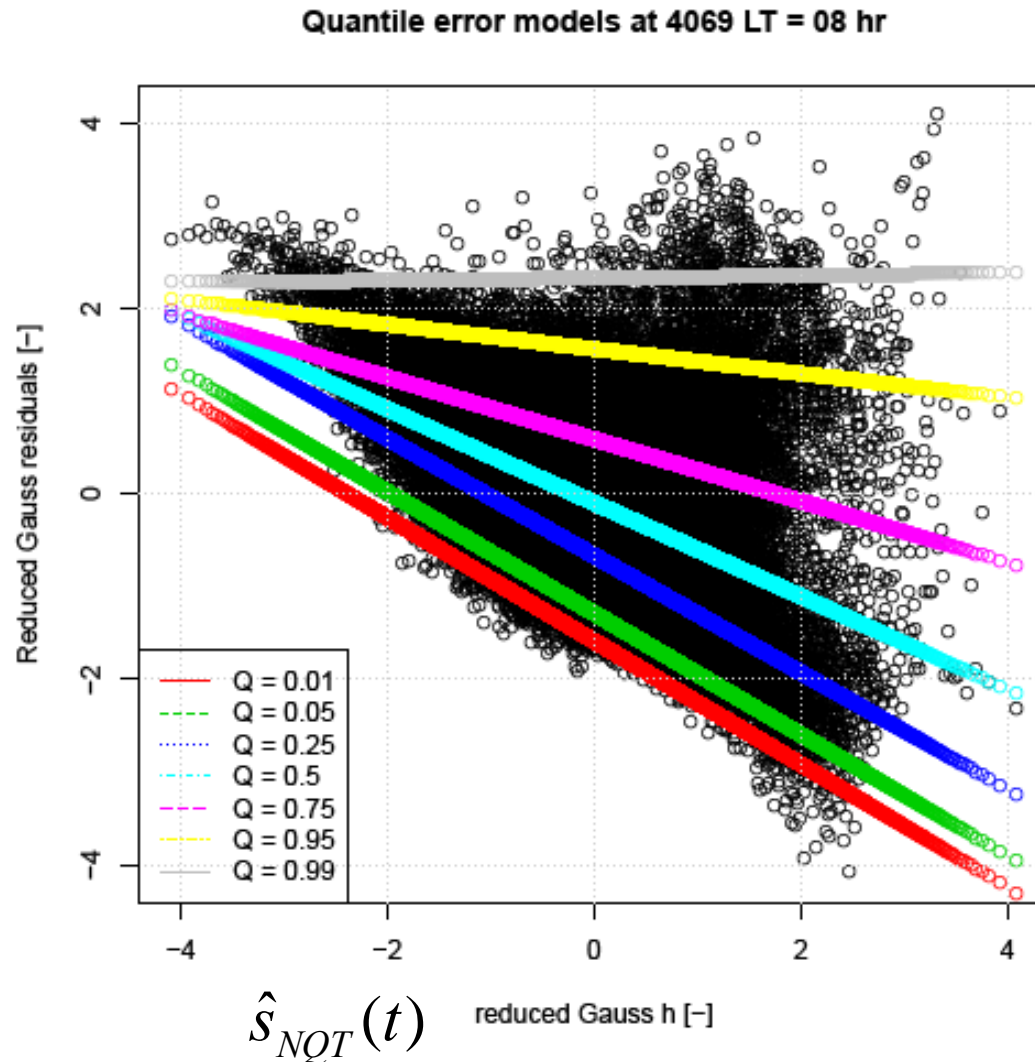
1. Sort the sample  $X$  from the smallest to the largest observation,  $x_{(1)}, \dots, x_{(n)}$ .
2. Estimate the cumulative probabilities,  $p_{(1)}, \dots, p_{(n)}$ , such that  $p_{(i)} = Pr(X \leq x_{(i)})$
3. Transform each  $x_{(i)}$  of  $X$  into  $y_{(i)} = Q^{-1}(p_{(i)})$  of the standard normal variate  $Y$ .

(e.g. Bogner et al. 2012, Hydrol. Earth Syst. Sci.)



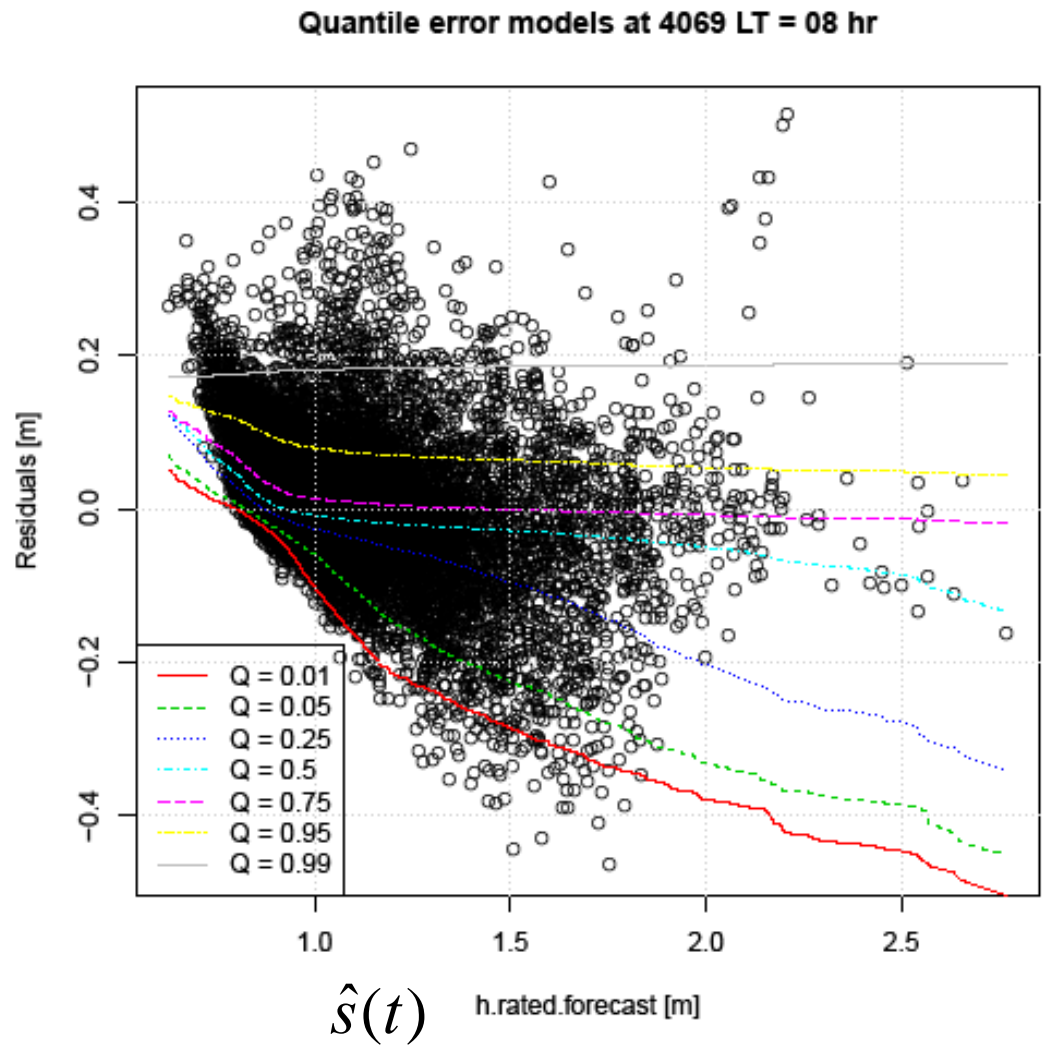
# Transformed data and fitted quantiles

$$e_{NQT}(t)$$

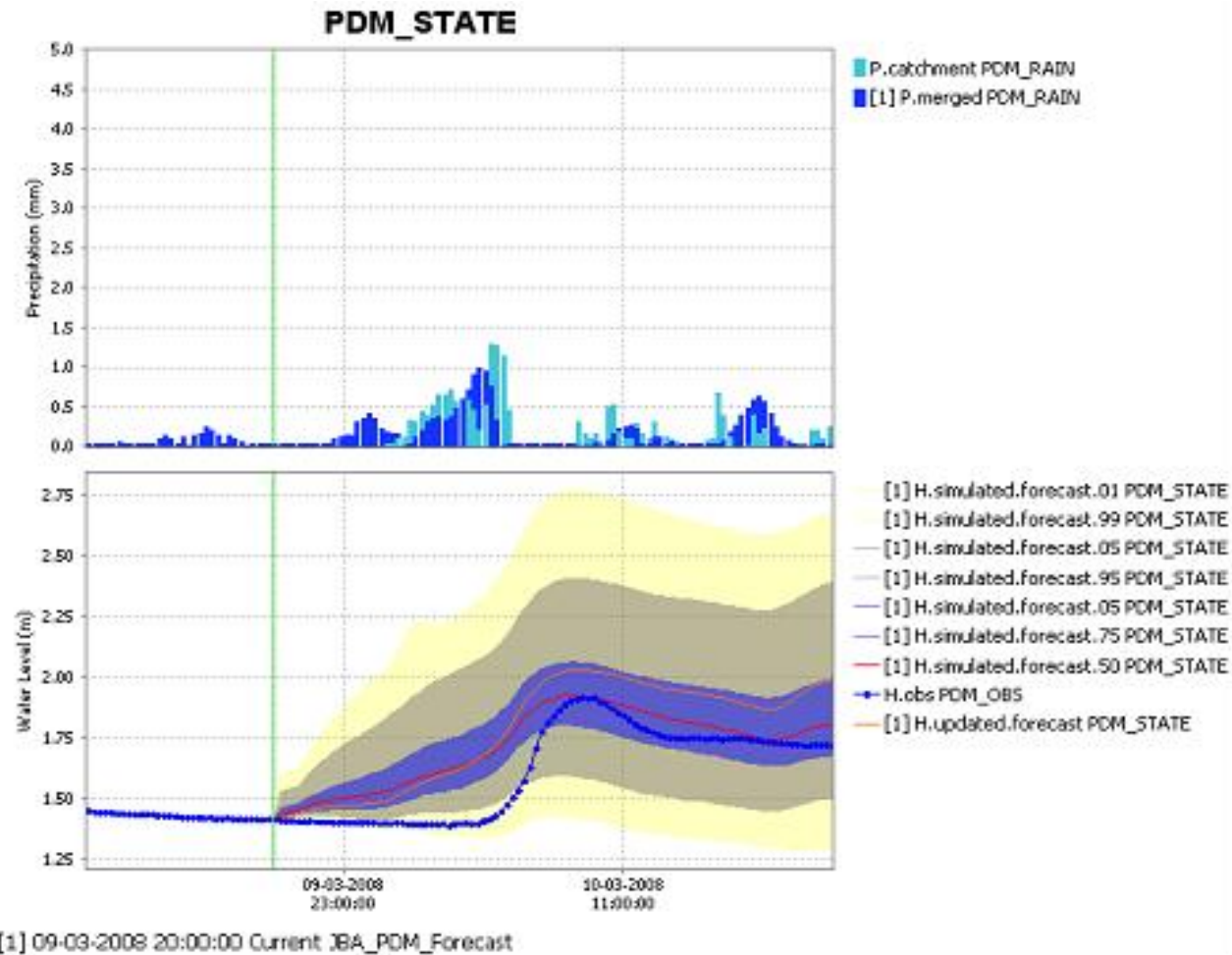


# Back transformed data and quantiles

$e(t)$



# Example of HFPT in NFFS (again)



# Problems found

# HFPT – what works

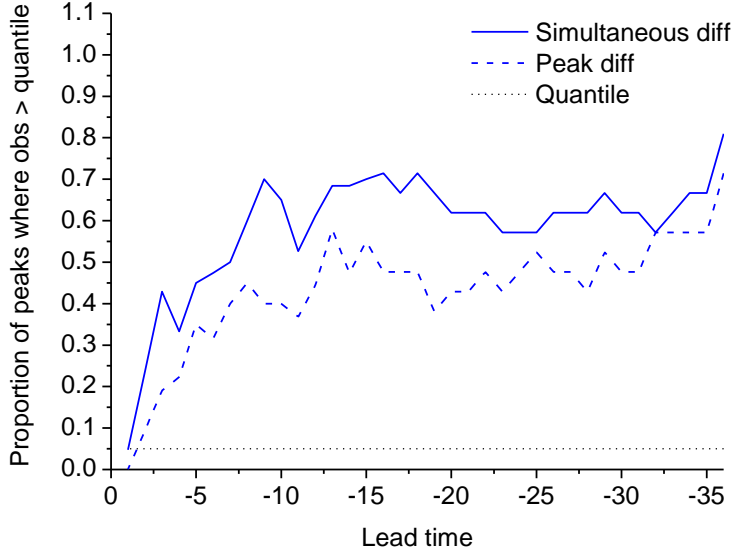
- ➔ Weerts et al. (2011) and R&D project
  - ➔ Approx 20 sites
  - ➔ 2 years calibration (forecast origins every 2(?) hours)
  - ➔ 2 years validation – predicted quantiles contained (roughly) the right proportion of observations (for most sites)
- ➔ JBA consulting carried out a similar analysis
  - ➔ 10 sites / range of catchment types
  - ➔ Much longer period of record
  - ➔ Same conclusion

# HFPT – what doesn't work

- ➔ Events & peaks of most interest
- ➔ Further analysis looked at peak and event behaviour
- ➔ High proportion of peaks exceeding the highest quantile (95%)

# Peak exceedence

- More peaks exceed the upper quantiles than expected



# What does this mean?

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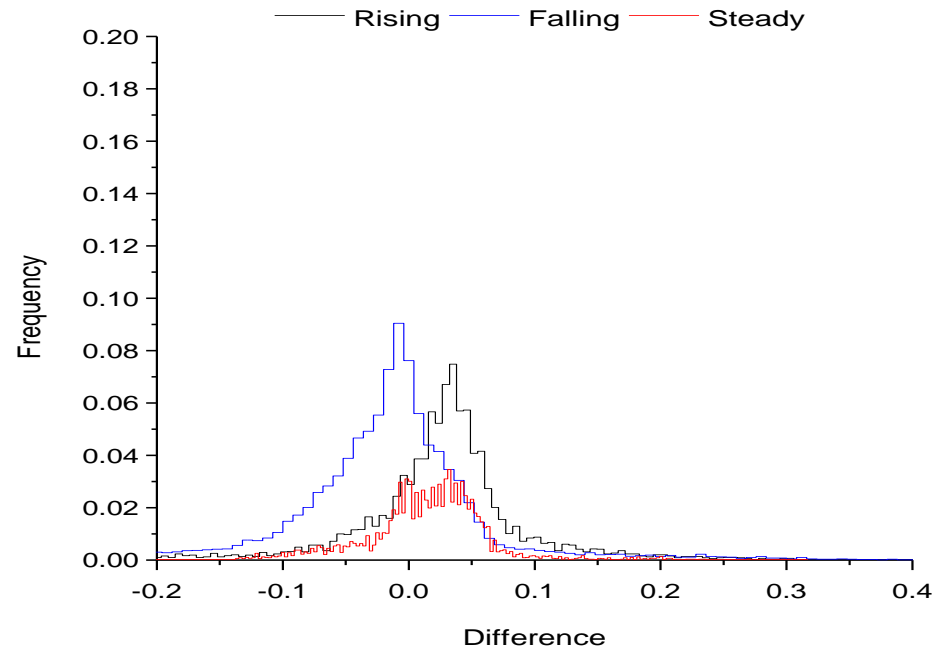
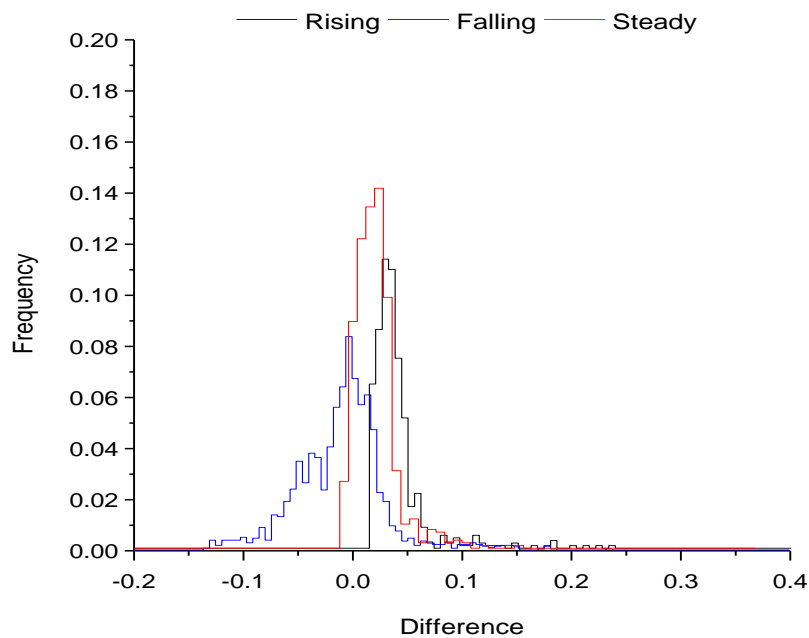
- Plume is not representative of behaviour at the peak
- It DOES mean:
  - “over all forecasts made, there is a 5% probability that any one observation will fall above the 95% quantile”
- It does NOT mean that:
  - “there is a 95% probability that the observed line will sit below the quantile for this forecast”



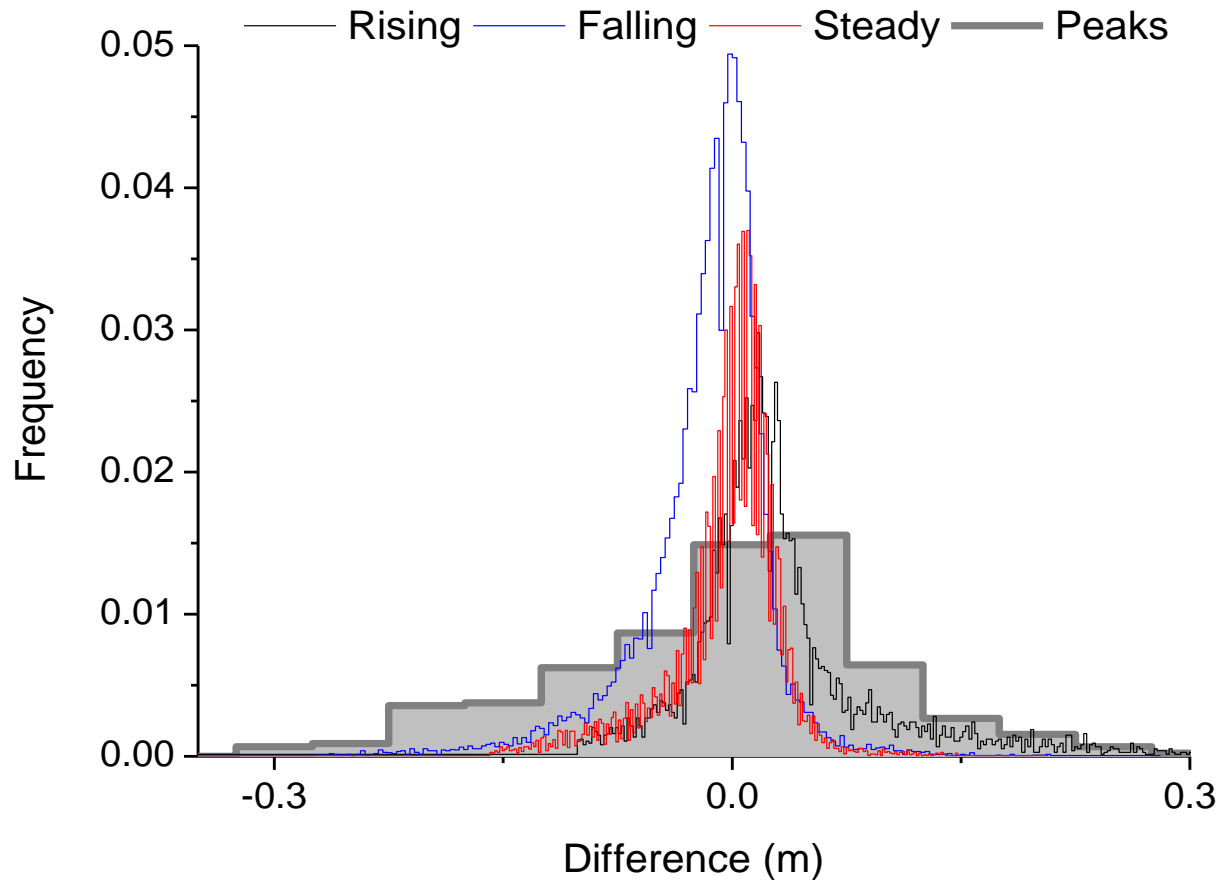
# Possible explanations

# Heteroscedacity

- Errors are different for different parts of a flood event
- Frequency distribution at a lead time for forecast & observed rain (single lead time)

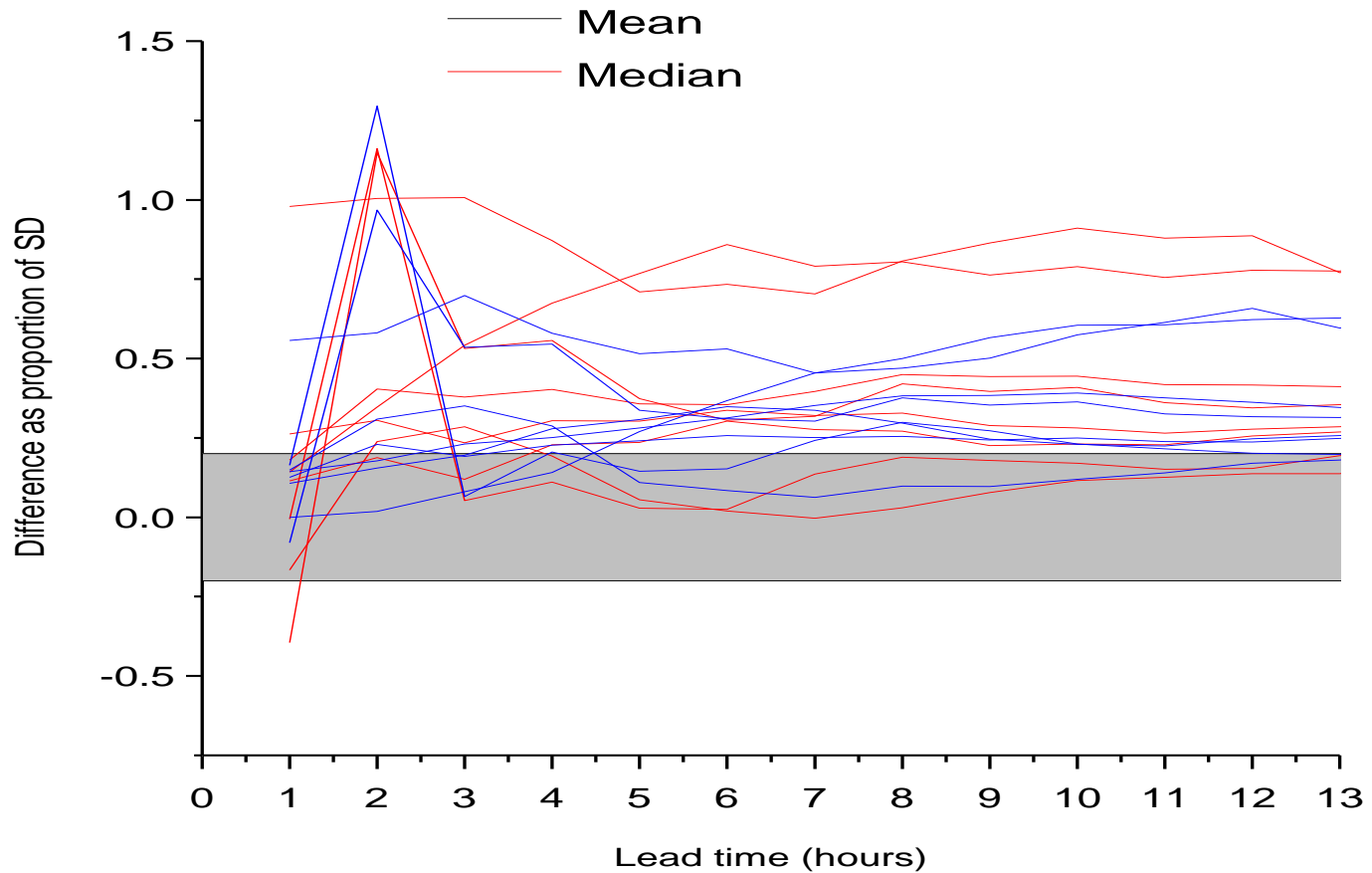


- Including errors in peaks as well (single lead time)



# All Tame forecast locations

- Forecast rain



# Reasons

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- Errors smallest when river receding (no rain)
- Recession over represented in sample (longer than rise)
- Observed/forecast rainfall errors more prominent at/before peak
- Error correction more problematic on the rise
- Timing errors more of a problem on the rise/peak
- Data heavily autocorrelated – all pairs are not equal (but are treated as such)

# Possible solutions

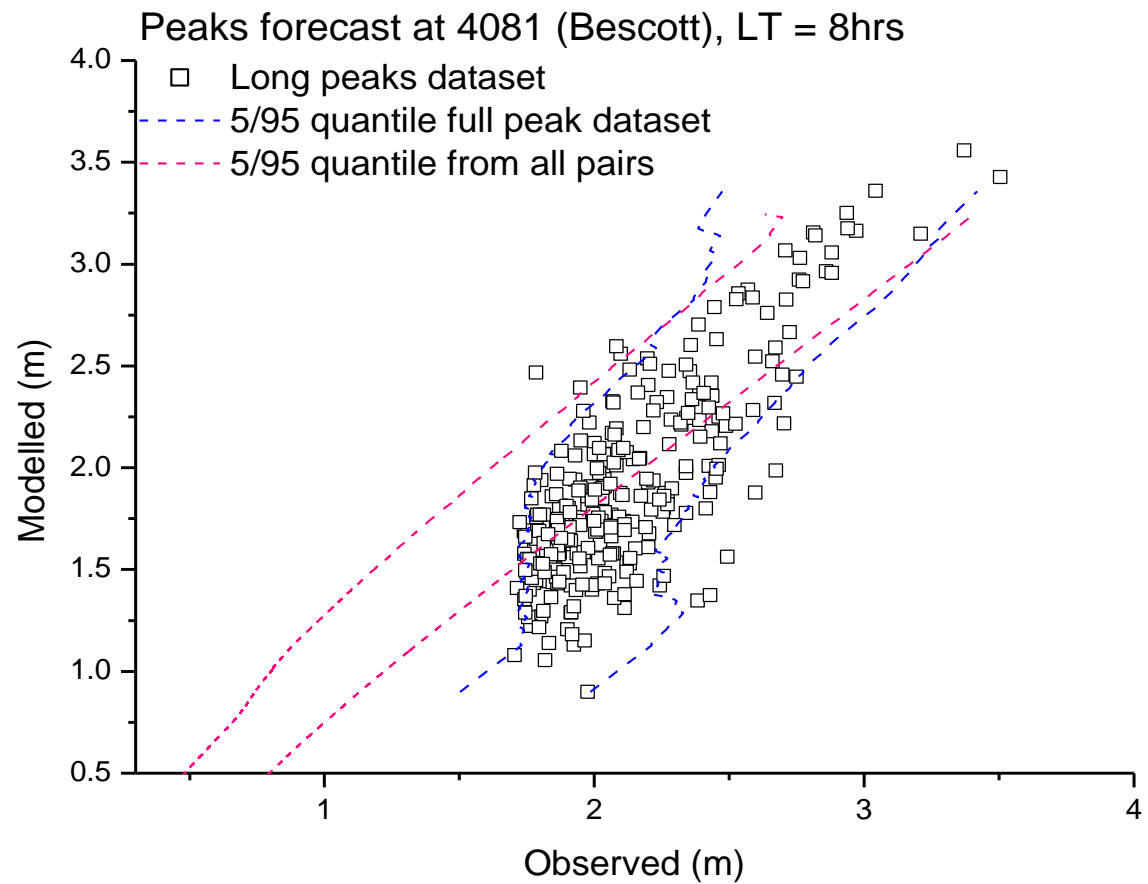
# Alternative QR datasets

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- Peaks – magnitude of difference, ignoring timing error
  - One point per event, per lead time for a specific, crucial, point in the forecast
  - May enable a probabilistic interpretation of the forecast peak and its timing
  - Potential problems:
  - Small dataset
  - Still sensitive to sampling approach and assumptions about linearity
  - Only (truly) applies to forecast peak (no plume)
  - -----
  - Pairs from rising limb
-

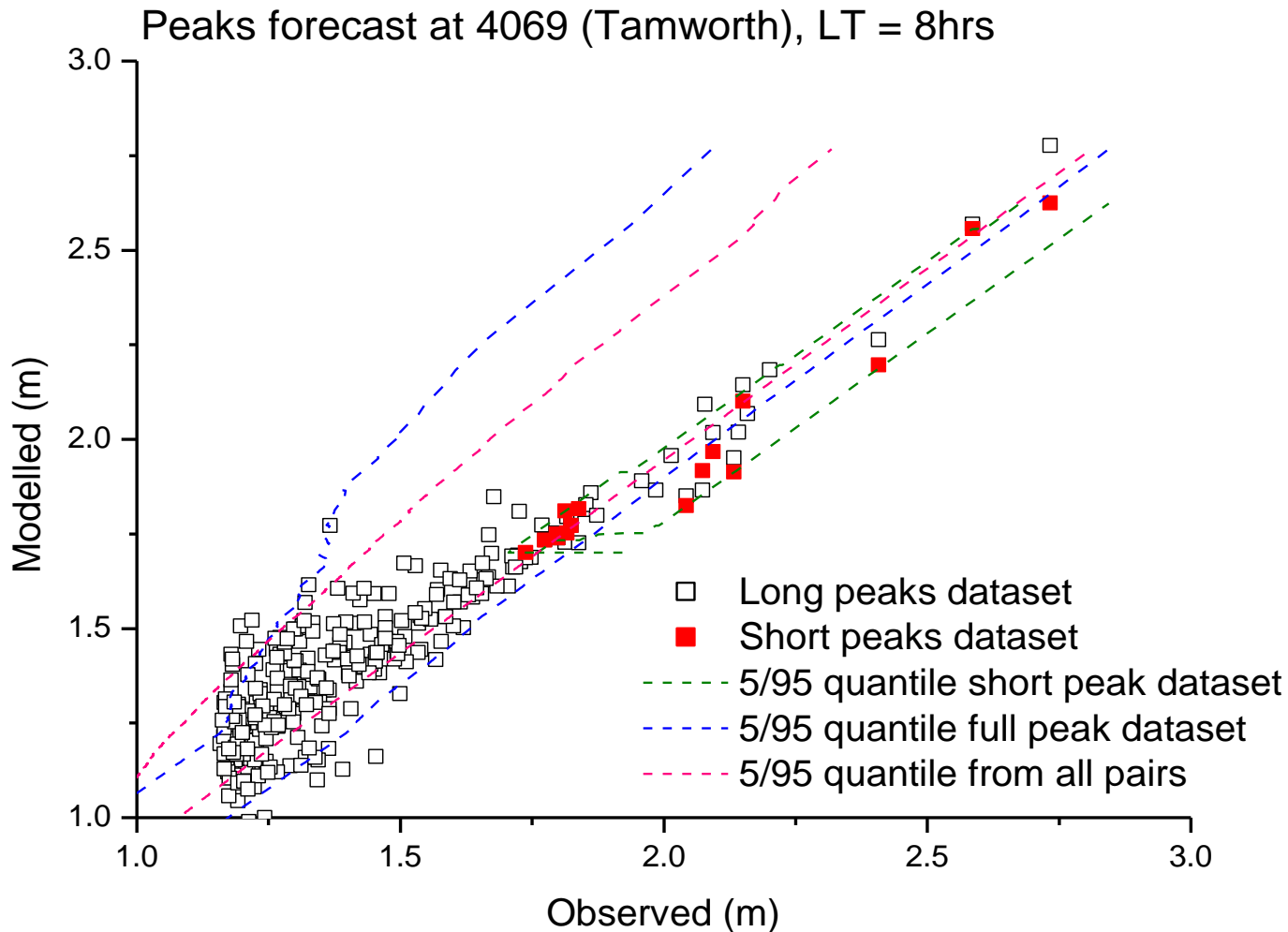
# Sampling just the peaks

- Pairs of peak modelled/observed data for single lead time





# Linear model a potential problem?



# Summary

# Conclusions

- ➔ Appears that HFPT / QR, in it's current form, doesn't deliver what users expect
  - ➔ Non-stationarity
  - ➔ QR assumptions
- ➔ Modifications possible, but further investigation needed
- ➔ Users interested in derived quantities, rather than the whole hydrograph

# Questions

- ➡ Can the HFPT approach be adapted to give us what we need?
- ➡ If so, what needs to be done?

# The Test Dataset

- ➔ Observed and forecast stage data for one site
  - ➔ Time series
  - ➔ Pairs for given lead-times & (by rising / falling)
- ➔ R script for creating quantile look-up tables
- ➔ Quantile fit plots
- ➔ Look-up tables
- ➔ Metadata
- ➔ Catchment map
- ➔ Presentation / problem statement